

• Vector

$$\langle \vec{v}, \vec{w} \rangle = \sum_{i=1}^n v_i w_i$$

• Matrix-Vector product

$$\vec{u} = \begin{bmatrix} u_1 \\ u_2 \\ \vdots \\ u_n \end{bmatrix} \quad A \text{ } m \times n \text{ matrix}$$

$$A\vec{u} = \begin{bmatrix} \sum_{j=1}^n a_{1j} u_j \\ \vdots \\ \sum_{j=1}^n a_{mj} u_j \end{bmatrix} \quad m \times 1$$

• column-form

$$A \text{ } m \times n \quad \vec{w} \text{ } n \times 1$$

$$A = [\vec{a}_1, \vec{a}_2, \dots, \vec{a}_n]$$

$$A\vec{w} = w_1 \vec{a}_1 + w_2 \vec{a}_2 + \dots + w_n \vec{a}_n$$

三种表示: $A = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \quad \vec{x} = \begin{pmatrix} 5 \\ 6 \end{pmatrix}$

$A\vec{x} =$
① 按行点积 $A\vec{x} = \begin{pmatrix} (1,2) \cdot \begin{pmatrix} 5 \\ 6 \end{pmatrix} \\ (3,4) \cdot \begin{pmatrix} 5 \\ 6 \end{pmatrix} \end{pmatrix} = \begin{pmatrix} 17 \\ 39 \end{pmatrix}$

② 线性组合 系数 * 基向量 $A\vec{x} = 5 \cdot \begin{pmatrix} 1 \\ 3 \end{pmatrix} + 6 \begin{pmatrix} 2 \\ 4 \end{pmatrix} = \begin{pmatrix} 17 \\ 39 \end{pmatrix}$

③ 矩阵

• Matrix

• lower/upper triangular matrix

↓
左下 右上

Diagonal matrix $\forall i \neq j \quad D_{i,j} = 0$

只有对角线上的元素可能不为0

1. prove $(AB)C = A(BC)$

$$A: m \times n \quad B: n \times r \quad C: r \times s$$

$$D = AB \quad E = BC$$

$$\Rightarrow \text{show } DC = AE$$

$$DC = \sum_{k=1}^r d_{i,k} c_{k,j} = \sum_{k=1}^r \left(\sum_{l=1}^n a_{i,l} b_{l,k} \right) c_{k,j}$$

$$AE = \sum_{k=1}^n a_{i,k} \cdot e_{k,j} = \sum_{k=1}^n a_{i,k} \left(\sum_{l=1}^r b_{k,l} c_{l,j} \right)$$

$$\Rightarrow DC = AE$$

2. transpose

prove $(AB)^T = B^T A^T$

$$(AB)^T_{i,j} = (AB)_{j,i} = \sum_{k=1}^n A_{j,k} \cdot B_{k,i}$$

$$(B^T A^T)_{i,j} = \sum_{k=1}^n (B^T)_{i,k} (A^T)_{k,j} = \sum_{k=1}^n B_{k,i} \cdot A_{j,k} = \sum_{k=1}^n A_{j,k} \cdot B_{k,i}$$

3. Symmetric matrix 对称矩阵 $A^T = A$

4. matrix inverse 逆矩阵 A^{-1}

$$B = A^{-1} \Rightarrow AB = BA = I$$

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \quad (ad \neq bc)$$

$$\Rightarrow A^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

① B is unique

Assume $\begin{cases} AB=BA=I \\ AC=CA=I \end{cases} A \neq C$

$$B = BI = BAC = IC = C$$

② $Ax=b \quad x=A^{-1}b$ (unique)

Assume $\begin{cases} Ax=b \\ Ay=b \end{cases} (x=y) \Rightarrow \begin{aligned} A(x-y) &= \vec{0} \\ A^{-1} \cdot A(x-y) &= \vec{0} \\ x &= y \end{aligned}$

③ diagonal matrix

$$\begin{pmatrix} a_{11} & 0 & \dots & 0 \\ 0 & a_{22} & & \vdots \\ \vdots & & \ddots & \\ 0 & 0 & \dots & a_{nn} \end{pmatrix}^{-1} = \begin{pmatrix} \frac{1}{a_{11}} & 0 & \dots & 0 \\ 0 & \frac{1}{a_{22}} & & \vdots \\ \vdots & & \ddots & \\ 0 & 0 & \dots & \frac{1}{a_{nn}} \end{pmatrix}$$

A triangular matrix is invertible iff the diagonal entries are invertible

④ $(AB)^{-1} = B^{-1}A^{-1}$

$$\begin{aligned} (B^{-1}A^{-1}) \cdot AB &= B^{-1}(A^{-1}A)B = B^{-1}B = I \\ AB \cdot (B^{-1}A^{-1}) &= A(BB^{-1})A^{-1} = AA^{-1} = I \end{aligned} \Rightarrow (A_1 A_2 \dots A_k)^{-1} = A_k^{-1} \dots A_2^{-1} A_1^{-1}$$

[e.g.] let $M=ABC$ where $A, B, C \in \mathbb{R}^{n \times n}$. Show M is invertible iff A, B, C are all invertible

① M invertible $\rightarrow A, B, C$ invertible

let $MN = (ABC)N = I \quad A^{-1} = BCN \Rightarrow A$ is invertible

$A^{-1} \cdot A = BCN A = I \Rightarrow B^{-1} = CNA \Rightarrow B$ is invertible

$B^{-1} \cdot B = CNA B = I \Rightarrow C^{-1} = NAB \Rightarrow C$ is invertible

② A, B, C invertible $\rightarrow M$ invertible

$$A^{-1}A = BB^{-1} = CC^{-1} = I$$

$$M(C^{-1}B^{-1}A^{-1}) = I \Rightarrow M^{-1} = C^{-1}B^{-1}A^{-1} \quad M \text{ is invertible}$$

• 矩阵乘法的几何意义

<1> 左乘 $Aa=b$ b 为 A 的列向量组 $\{b_1, b_2, \dots, b_n\}$ 的线性组合

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = x \begin{bmatrix} a \\ c \end{bmatrix} + y \begin{bmatrix} b \\ d \end{bmatrix}$$

<2> 右乘 $a^T A^T = b^T$ b^T 为 A 的行向量组 $\{b^{(1)}, b^{(2)}, \dots, b^{(m)}\}$ 的线性组合

$$\begin{bmatrix} x & y \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = x \begin{bmatrix} a & b \end{bmatrix} + y \begin{bmatrix} c & d \end{bmatrix}$$

<3> 进一步地 $C = AB$ $C_j = A \cdot B_j$ [类似左乘]

$\Rightarrow C_j$ 是矩阵 A 的列向量的线性组合

$$C_{(i)} = A_i \cdot B \text{ [类似右乘]}$$

$\Rightarrow C_{(i)}$ 是矩阵 B 的行向量的线性组合

$$\Rightarrow C = \sum_{i=1}^3 A_i \cdot B_{(i)} \quad \begin{matrix} 3 \times 2 \\ \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix} \end{matrix} \cdot \begin{matrix} 2 \times 2 \\ \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \end{matrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} \cdot \begin{bmatrix} 1 & 2 \end{bmatrix} + \begin{bmatrix} 4 \\ 5 \\ 6 \end{bmatrix} \cdot \begin{bmatrix} 3 & 4 \end{bmatrix}$$

[e.g.1] 见 rank ⑤ 证明

[e.g.2] let $v_1, v_2, \dots, v_d$ be a basis of a subspace $V \in \mathbb{R}^m$

show for any list of vectors $a_1, \dots, a_n$ in V . $\exists X \in \mathbb{R}^{d \times n}$

$$\text{s.t. } [a_1, \dots, a_n] = [v_1, \dots, v_d] X$$

$$a_i = [v_1, \dots, v_d] \cdot x_i$$

$$= x_{i1} v_1 + x_{i2} v_2 + \dots + x_{id} v_d$$

is a linear combination $a_i \in \text{span}\{v_1, v_2, \dots, v_d\}$

• GJ-E 的过程

- ① Forward elimination (get an upper triangular matrix) REF
 ② Backward substitution (get a diagonal matrix) RREF $\Rightarrow \begin{bmatrix} I_k & F \\ 0 & 0 \end{bmatrix}$ 非自由的
自由变量

• elementary row operations 初等行变换

- ① multiplication $A_i \leftarrow CA_i$ ② addition $A_i \leftarrow A_i + \beta A_j$ ③ interchange $\begin{pmatrix} A_i \\ A_j \end{pmatrix} \leftarrow \begin{pmatrix} A_j \\ A_i \end{pmatrix}$

e.g. $\begin{bmatrix} 1 & 0 & 0 \\ 0 & \alpha & 0 \\ 0 & 0 & 1 \end{bmatrix} \alpha A_2$ $\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ \beta & 0 & 1 \end{bmatrix} A_3 + \beta A_1$ $\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} A \Leftrightarrow A_2$

elementary matrix $\Rightarrow$ a single elementary row operation

the inverse of elementary matrix $\Rightarrow$ reverse operation

$$\begin{cases} E_{R_i R_j}^{-1} = E_{R_i R_j} \\ E_{\alpha R_i}^{-1} = E_{\frac{1}{\alpha} R_i} \\ E_{\beta R_i + R_j}^{-1} = E_{- \beta R_i + R_j} \end{cases}$$

A is invertible $\Leftrightarrow n$ pivots exist in Gauss-Jordan elimination

• if $MA = I_n$. M is invertible, show $A^{-1} = M$.

$$M^{-1} \cdot MA = M^{-1} \Rightarrow A = M^{-1} \quad AM = M^{-1} \cdot M = I$$

$$\begin{cases} MA = I_n \\ AM = I_n \end{cases} \Rightarrow A \text{ is invertible and } A^{-1} = M$$

• A is invertible iff. $Ax=0$ has a unique solution $x=0$

① $\Leftarrow$ "if" G.J-E $(A|0) \Rightarrow$ augmented matrix $(I|0)$

$\exists$ elementary matrices $E_1 \dots E_p A = I \Rightarrow A$ is invertible

② $\Rightarrow$ "only if"

Assume A is invertible

$$Ax=0 \Rightarrow A^{-1}Ax = Ix = 0 \Rightarrow x=0$$

• calculate A^{-1}

① $A \xrightarrow{E_1 \dots E_k} U \xrightarrow{E_{k+1} \dots E_p} I \quad A^{-1} = E_p \dots E_2 E_1$

② $[A | I] \Rightarrow [I | A^{-1}]$

e.g. $A = \begin{bmatrix} 1 & 4 & 3 \\ -1 & 2 & 0 \\ 2 & 2 & 3 \end{bmatrix}$

$$[A | I] = \left[\begin{array}{ccc|ccc} 1 & 4 & 3 & 1 & 0 & 0 \\ -1 & 2 & 0 & 0 & 1 & 0 \\ 2 & 2 & 3 & 0 & 0 & 1 \end{array} \right] \rightarrow \left[\begin{array}{ccc|ccc} 1 & 0 & 0 & \frac{1}{2} & -\frac{1}{2} & \frac{1}{2} \\ 0 & 1 & 0 & \frac{3}{4} & -\frac{1}{4} & -\frac{1}{4} \\ 0 & 0 & 1 & \frac{1}{6} & \frac{1}{2} & \frac{1}{6} \end{array} \right]$$

• A is invertible [equivalent statements]

$\int Ax=0$ has a unique solution $x=0$

A is a product of elementary matrices

A has n pivots

the columns of A $\left\{ \begin{array}{l} \text{span } \mathbb{R}^n \\ \text{are linearly independent} \\ \text{form a basis} \end{array} \right.$

$\dim(C(A))=n$

$Ax=b$ is solvable for any b

• linear space

1. two operations addition & scalar multiplication

2. 8 axioms:

① $u+v=v+u$

② $u+(v+w)=(u+v)+w$

③ element $0 \Rightarrow u+0=u$

④ $-u$ exists $\Rightarrow u+(-u)=0$

⑤ $\alpha(u+v)=\alpha u+\alpha v$

⑥ $(\alpha+\beta)u=\alpha u+\beta u$

⑦ $\alpha(\beta u)=(\alpha\beta)u$

⑧ exists $1 \quad 1u=u$

3. subspace W is a subspace of $V \leftarrow$ a linear space if:

① W is a subset of V

② W is a linear space

$\uparrow$
need to contain W

• V is a subset of V

• $\{0\}$ is a subspace of $\mathbb{R}^n$

① $0+0=0 \Rightarrow$ in $\{0\}$

② $c \cdot 0=0 \quad (\forall c \in \mathbb{R})$ in $\{0\}$

③ have 0 element

4. $Ax=b$ has a solution iff $b \in C(A)$.

$r(A)=r([A|b])$

let $A=(a_1, \dots, a_n)$

① $Ax=b$ has a solution $x=\begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \quad a_1x_1+\dots+a_nx_n=Ax=b \in \text{Span}\{a_1, \dots, a_n\}=C(A)$

② $b \in C(A)=\text{Span}\{a_1, \dots, a_n\} \quad \exists \alpha_1, \dots, \alpha_n \in \mathbb{R} \quad b=\alpha_1a_1+\dots+\alpha_na_n$

$\Rightarrow \alpha$ is a solution to $Ax=b$

• $Ax=y$ 值域 $\Rightarrow C(A)$

$[y = x_1 a_1 + x_2 a_2 + \dots + x_n a_n]$
 每个y至多有1个x对应

$x^T A = y^T$ 值域 $R(A)$

$[y^T = x_1 a^{(1)} + x_2 a^{(2)} + \dots + x_m a^{(m)}]$
 每个y至少有1个x对应

函数	单射	满射	双射
$Ax=y$	列满秩	行满秩	满秩
$x^T A = y^T$	行满秩	列满秩	

-- 对应才可能有逆矩阵存在

★判断解的个数 $Ax=b$

$A \in \mathbb{R}^{n \times m}$ $b \in \mathbb{R}^{n \times 1}$

① 是否有解

$\text{rank}(A) = \text{rank}(A|b) \Rightarrow b \in C(A)$ 行满秩 $\rightarrow$ 一定有解

Proof: full row rank $\Leftrightarrow Ax=y$ 满射 值域为 $CO(A)$

$\Rightarrow b \in C(A)$

② 解的个数

$A \in \mathbb{R}^{m \times n}$ 1° $\text{rank}(A) = \text{rank}(A|b) = n$ 唯一解

列满秩 $\Rightarrow$ 单射

2° $\text{rank}(A) = \text{rank}(A|b) < n$ 非单射 无数解

[e.g.] $A \in \mathbb{R}^{m \times n}$ of rank r , how many solutions could have in $Ax=b$?

① $m=n=r=6$ One Solution $C(A)$ fill $\mathbb{R}^6$ $b \in \mathbb{R}^6 \Rightarrow b \in C(A)$

② $m=9, n=r=7$

<1> $b \notin C(A)$ 0 Solution <2> $b \in C(A)$ no free variables 1 Solution

③ $m=r=7, n=8$

$C(A)$ fill $\mathbb{R}^7$ $b \in \mathbb{R}^7 \Rightarrow b \in C(A)$ $r < n$ ∞ solutions

④ $m=n=8, r=7$

<1> $b \notin C(A)$ 0 solution

<2> $b \in C(A)$ ∞ solutions

③ 解集 solution set

$$Ax=b \quad x = \underbrace{p}_{\text{特解}} + N(A)$$

<1> $A(p + N(A)) = A(p) + A(N(A)) = b + 0 = b$

<2> assume p' satisfied $Ap' = b$

$$A(p' - p) = 0 \quad p' - p \in N(A) \Rightarrow p' \in p + N(A)$$

$$\Rightarrow Ax=b \text{ 's solution set : } x = p + N(A)$$

• rank

tough proof: $\text{rank} \langle a_1 + b_1, \dots, a_n + b_n \rangle \leq \text{rank} \begin{pmatrix} a_1 & \dots & a_n \\ b_1 & \dots & b_n \end{pmatrix} = \text{rank}(A) + \text{rank}(B)$

① $0 \leq \text{rank}(A_{m \times n}) \leq \min\{n, m\}$

② $\text{rank}(A+B) \leq \text{rank}(A) + \text{rank}(B)$

③ $\text{rank} \begin{pmatrix} A & 0 \\ 0 & B \end{pmatrix} = \text{rank} \begin{pmatrix} A' & 0 \\ 0 & B' \end{pmatrix} = \text{rank}(A) + \text{rank}(B) \quad (A', B' \text{ RREF})$

elementary row operations don't change rank

if P, Q has a full rank $\Rightarrow \text{rank}(PA) = \text{rank}(AQ) = \text{rank}(PAQ) = \text{rank}(A)$

④ $\text{rank}(A) = \text{rank}(A^T)$

$$R(A) = C(A) = \text{rank}(A)$$

⑤ $\text{rank}(AB) \leq \min\{\text{rank}(A), \text{rank}(B)\}$

线性变换

$$\text{let } C = AB$$

$$C_{i,j} = \sum_{k=1}^m a_{i,k} \cdot b_{k,j} \quad \text{then we can see it as linear combination}$$

<1> $C_i = A \cdot B_i \quad (i=1, 2, \dots, p)$

$$= (A_1, A_2, \dots, A_m) \cdot \begin{bmatrix} b_{1,i} \\ b_{2,i} \\ \vdots \\ b_{m,i} \end{bmatrix} = b_{1,i} \cdot A_1 + b_{2,i} \cdot A_2 + \dots + b_{m,i} \cdot A_m$$

$$\Rightarrow \text{rank}(C) = \text{rank}(AB) \leq C(A) = \text{rank}(A)$$

<2> $C(i) = A(i) \cdot B \quad (i=1, 2, \dots, n)$

$$= [a_{i,1}, a_{i,2}, \dots, a_{i,m}] \cdot \begin{bmatrix} b_{1,1} \\ b_{1,2} \\ \vdots \\ b_{1,m} \end{bmatrix} = a_{i,1} \cdot b_{1,1} + a_{i,2} \cdot b_{1,2} + \dots + a_{i,m} \cdot b_{1,m}$$

$$\Rightarrow \text{rank}(C) = \text{rank}(AB) \leq R(B) = \text{rank}(B)$$

$$[I_n \ 0] \quad A \in \mathbb{R}^{m \times n} \quad B \in \mathbb{R}^{n \times k}$$

$$\begin{bmatrix} I_n & 0 \\ -A & I_m \end{bmatrix} \begin{bmatrix} I_n & -B \\ A & 0 \end{bmatrix} \begin{bmatrix} I_n & B \\ 0 & I_p \end{bmatrix}$$



$$\text{rank}(AB) \geq \text{rank}(A) + \text{rank}(B) - n$$

$$1) \quad n + \text{rank}(AB) = \text{rank} \left(\begin{bmatrix} I_n & 0 \\ 0 & AB \end{bmatrix} \right) = \text{rank} \left(\begin{bmatrix} I_n & -B \\ A & 0 \end{bmatrix} \right) \geq \text{rank}(A) + \text{rank}(B)$$

2) another proof using rank-nullity theorem.

$$A \in \mathbb{R}^{n \times p}, B \in \mathbb{R}^{p \times q}, AB \in \mathbb{R}^{n \times q}$$

$$\text{if } x \in N(B), Bx=0 \Rightarrow ABx=0 \Rightarrow x \in N(AB)$$

$$\Rightarrow N(B) \subseteq N(AB) \quad \dim(N(B)) \leq \dim(N(AB))$$

$$\text{if } x \notin N(B), x \in N(A) \Rightarrow x \in N(AB)$$

$$N(AB) \subseteq N(B) \cup B^{-1}(N(A)) \Rightarrow \dim(N(AB)) \leq \dim(N(A)) + \dim(N(B))$$

$$\Rightarrow \dim[B^{-1}(N(A))] \leq \dim(A)$$

$$\text{rank}(AB) = q - \dim(N(AB)), \text{rank}(A) = p - \dim(N(A))$$

$$\text{rank}(B) = q - \dim(N(B))$$

$$\Rightarrow q - \text{rank}(AB) \leq p + q - (\text{rank}(A) + \text{rank}(B))$$

$$\Rightarrow \text{rank}(AB) \geq \text{rank}(A) + \text{rank}(B) - p$$

$$\text{rank}(ABC) = \text{rank}(AB) + \text{rank}(BC) - \text{rank}(B)$$

$$\text{rank}(B) + \text{rank}(ABC) = \text{rank} \left(\begin{bmatrix} B & 0 \\ 0 & ABC \end{bmatrix} \right) = \text{rank} \left(\begin{bmatrix} BC & B \\ 0 & AB \end{bmatrix} \right) \geq \text{rank}(AB) + \text{rank}(BC)$$

$$(b) \quad \text{rank}(I - AB) \leq \text{rank}(I - A) + \text{rank}(I - B)$$

$$\text{rank}(I - AB) = \text{rank}(I - A + A - AB) \leq \text{rank}(I - A) + \text{rank}(A - AB)$$

$$\text{rank}(A - AB) = \text{rank}(A(I - B)) = \min \{ \text{rank}(A), \text{rank}(I - B) \} \leq \text{rank}(I - B)$$

$$\textcircled{7} \quad r(A) + r(C) \leq r \begin{pmatrix} A & B \\ 0 & C \end{pmatrix} \leq r(A) + r(B) + r(C)$$

$$\text{let } A \in \mathbb{R}^{m \times q}, C \in \mathbb{R}^{n \times n}$$

$$\text{the left } q \text{ column } r \begin{bmatrix} A \\ 0 \end{bmatrix} \geq r(A)$$

$$\text{the right } n \text{ column } r \begin{bmatrix} B \\ C \end{bmatrix} \geq r(C)$$

$$\Rightarrow r(A) + r(C) \leq r \begin{pmatrix} A & B \\ 0 & C \end{pmatrix}$$

$$\begin{bmatrix} A & B \\ 0 & C \end{bmatrix} = \underbrace{\begin{bmatrix} A & 0 \\ 0 & C \end{bmatrix}}_X + \underbrace{\begin{bmatrix} 0 & B \\ 0 & 0 \end{bmatrix}}_Y \Rightarrow \begin{cases} r(X) = r(A) + r(C) \\ r(Y) = r(B) \end{cases}$$

$$r(X+Y) \leq r(X) + r(Y) \Rightarrow r \begin{pmatrix} A & B \\ 0 & C \end{pmatrix} \leq r(A) + r(B) + r(C)$$

$\textcircled{8}$ every elementary matrix has a full rank

$\langle 1 \rangle I_n = \{e_1, e_2, \dots, e_n\}$ has a full rank

$\langle 2 \rangle \text{ let } R_1 \leftarrow R_1 + kR_2$

$$\alpha_1(e_1 + ke_2) + \alpha_2 e_2 + \dots + \alpha_n e_n = 0$$

$$\text{let } \alpha_1 \neq 0 \quad e_1 = -\frac{(\alpha_2 + k\alpha_1)e_2 + \alpha_3 e_3 + \dots + \alpha_n e_n}{\alpha_1}$$

which contradicts with $e_1, e_2, \dots, e_n$ is independent

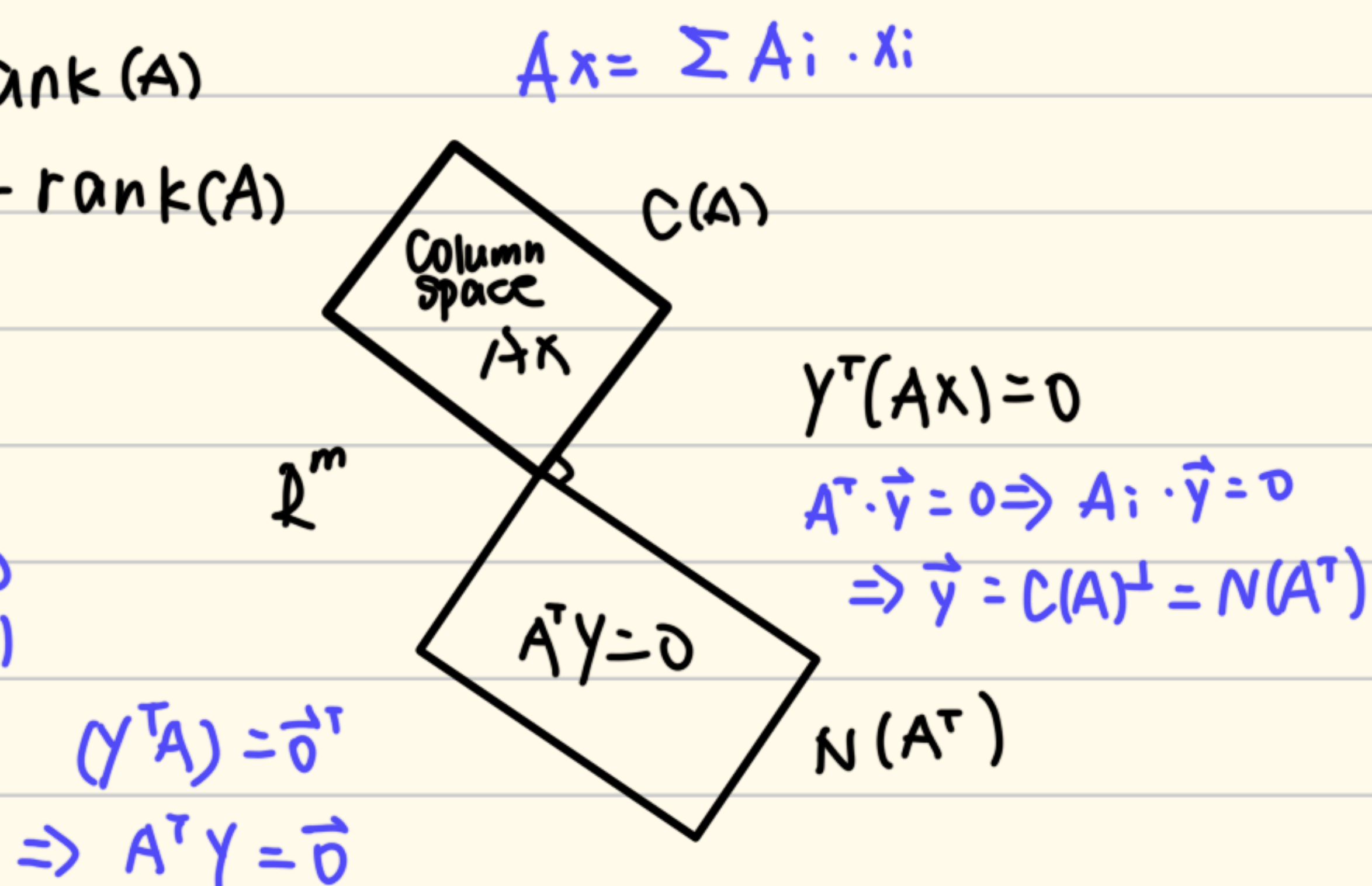
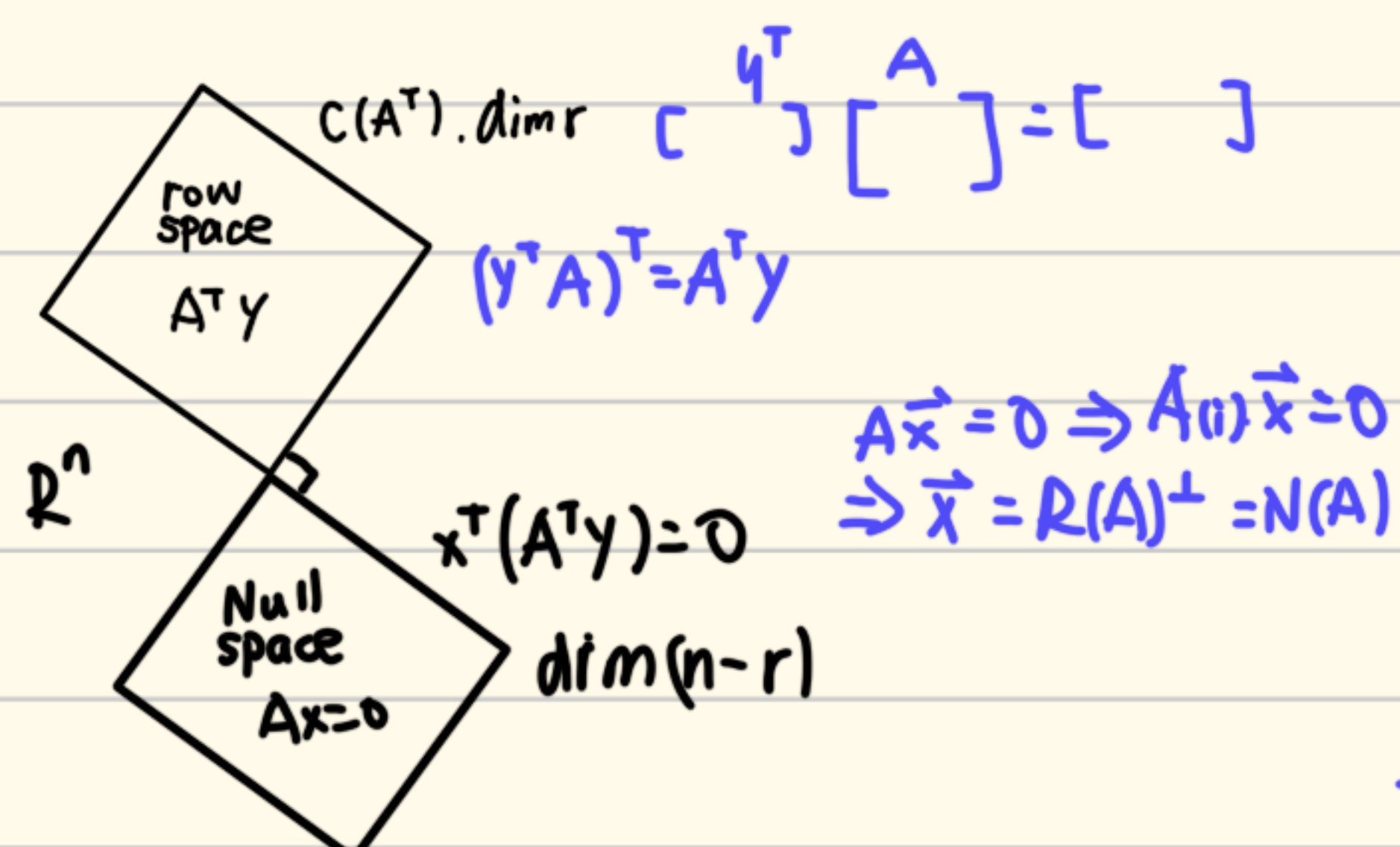
$$\Rightarrow \alpha_1 = \alpha_2 = \dots = \alpha_n = 0$$

$\langle 3 \rangle R_1 \leftrightarrow R_2, R_1 \leftarrow cR_1$ are same

$\textcircled{9}$ Fundamental Theorem

$$(1) N(A) = C(A)^\perp \quad \dim(N(A)) = n - \text{rank}(A)$$

$$(2) N(A^T) = R(A)^\perp \quad \dim(N(A^T)) = m - \text{rank}(A)$$



[e.g.1] $A \in \mathbb{R}^{m \times n}$. if $B \in \mathbb{R}^{r \times m}$. $BA = C$, $\text{rank}(B) = m$, show $\text{rank}(A) = \text{rank}(C)$

proof: $\langle 1 \rangle BAx = Cx = 0 \Rightarrow N(A) \subseteq N(C)$

$\langle 2 \rangle$ if $x \in N(C)$ $BAx = Cx = 0$ $\text{rank}(B) = m \rightarrow$ injective (单射)

$$BAx = 0 \Rightarrow Ax = 0 \quad N(C) \subseteq N(A)$$

$$\Rightarrow N(A) = N(C) \quad n - \text{rank}(A) = n - \text{rank}(C) \Rightarrow \text{rank}(A) = \text{rank}(C)$$

[e.g.2] $A, B \in \mathbb{R}^{n \times n}$. Prove:

$$\text{rank}(AB + A + B) \leq \text{rank}(A) + \text{rank}(B)$$

proof:
$$\begin{pmatrix} A & A+B \\ 0 & B \end{pmatrix} \begin{pmatrix} B & 0 \\ E & 0 \end{pmatrix} = \begin{pmatrix} AB+A+B & 0 \\ B & 0 \end{pmatrix}$$

$$\text{rank}(AB + A + B) \leq \text{rank} \begin{pmatrix} AB+A+B & 0 \\ B & 0 \end{pmatrix} \leq \begin{pmatrix} A & A+B \\ 0 & B \end{pmatrix} = \text{rank}(A) + \text{rank}(B)$$

[e.g.3] $A, B \in \mathbb{R}^{n \times n}$ if $AB = 0$, $r(A^2) = r(A)$, prove $\dim(C(A) \cap C(B)) = 0$

$$AB = 0 \Rightarrow C(B) \subseteq N(A)$$

Assume $x \in C(A) \cap N(A)$, $x \neq 0$ ①

$$\begin{cases} x \in C(A) \Rightarrow x = Ay \Rightarrow A^2y = 0 \\ x \in N(A) \Rightarrow Ax = 0 \end{cases} \quad \text{rank}(A^2) = \text{rank}(A) \Rightarrow N(A^2) = N(A)$$

$$\Rightarrow y \in N(A^2) \Rightarrow x = Ay = 0 \text{ which contradicts with ①}$$

$$\Rightarrow C(A) \cap C(B) \subseteq C(A) \cap N(A) = 0$$

• orthogonal

投影系数向量

投影向量: $Ay = A \cdot (A^T A)^{-1} A^T b$

for a least square problem $Ax = b$, suppose A has linearly independent columns, then the least square solution is $y = (A^T A)^{-1} A^T b$.

$$b - Ay \perp C(A) \Rightarrow (b - Ay)^T \cdot Ax = 0 \quad \forall x \in \mathbb{R}^{n \times 1}$$

$$\Rightarrow (b - Ay)^T A = 0 \Rightarrow A^T (b - Ay) = 0 \Rightarrow y = (A^T A)^{-1} A^T b$$

[e.g.] find the projection of $(2, 3, 2, 1)$ onto the nullspace of

$$A = \begin{bmatrix} 1 & 3 & 1 & 2 \\ 2 & 6 & 4 & 8 \\ 0 & 0 & 2 & 4 \end{bmatrix}$$

$$Ax = 0 \Rightarrow \begin{bmatrix} 1 & 3 & 0 & 0 \\ 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 \end{bmatrix} x = 0 \quad \text{the basis of } N(A): \left\{ \begin{bmatrix} -3 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ -2 \\ 1 \end{bmatrix} \right\}$$

$$V = \begin{bmatrix} -3 & 0 \\ 1 & 0 \\ 0 & -2 \\ 0 & 1 \end{bmatrix}$$

$$V^T V = \begin{bmatrix} 10 & 0 \\ 0 & 5 \end{bmatrix}$$

$$\text{projection} = V \cdot (V^T V)^{-1} V^T b$$

$$= \begin{bmatrix} \frac{9}{10} & -\frac{3}{10} & \frac{6}{5} & -\frac{3}{5} \end{bmatrix}^T$$

[e.g.] 3. Orthogonality

(10 points)

Suppose S is a subspace of $\mathbb{R}^n$. Suppose $\mathbf{b} \in \mathbb{R}^n$ and $\mathbf{p} \in S$ satisfy $(\mathbf{b} - \mathbf{p}) \perp S$. Prove that for any $\mathbf{z} \in S$, we have $\|\mathbf{b} - \mathbf{z}\|^2 - \|\mathbf{b} - \mathbf{p}\|^2 = \|\mathbf{z} - \mathbf{p}\|^2$.

Note that if $\mathbf{x} \perp \mathbf{y}$, then $\|\mathbf{x}\|^2 + \|\mathbf{y}\|^2 = \|\mathbf{x} + \mathbf{y}\|^2$

$$\|\mathbf{b} - \mathbf{z}\|^2 = \|\mathbf{b} - \mathbf{p} + \mathbf{p} - \mathbf{z}\|^2. \quad (\mathbf{b} - \mathbf{p}) \perp S. \quad \mathbf{p} - \mathbf{z} \in S \Rightarrow \mathbf{b} - \mathbf{p} \perp \mathbf{p} - \mathbf{z}$$

$$\Rightarrow \|\mathbf{b} - \mathbf{z}\|^2 = \|\mathbf{b} - \mathbf{p}\|^2 + \|\mathbf{z} - \mathbf{p}\|^2$$

2. $W \subset \mathbb{R}^n$. $\mathcal{B}$ is an orthonormal basis $\{\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_k\}$ of W . and a vector $\mathbf{v} \in \mathbb{R}^n$. the projection $\mathbf{p}$ of $\mathbf{v}$ on W is:

$$\mathbf{p} = \sum_{i=1}^n \langle \mathbf{w}_i, \mathbf{v} \rangle \mathbf{w}_i$$

$$\langle \mathbf{v} - \mathbf{p}, \mathbf{w}_i \rangle = 0 \Rightarrow (\mathbf{v} - \mathbf{p}) \cdot \mathbf{w}_i = \mathbf{v} \cdot \mathbf{w}_i - \mathbf{w}_i \cdot \sum_{j=1}^n \alpha_j \mathbf{w}_j$$

$$\mathbf{p} = \alpha_i \mathbf{w}_i$$

$$= \mathbf{v} \cdot \mathbf{w}_i - \mathbf{w}_i \cdot \alpha_i \mathbf{w}_i = 0$$

$$\Rightarrow \alpha_i = \mathbf{v} \cdot \mathbf{w}_i$$

$$\Rightarrow \mathbf{p} = \sum_{i=1}^n \langle \mathbf{w}_i, \mathbf{v} \rangle \mathbf{w}_i$$

3. orthogonal matrix

<1> $\mathbf{y} = \mathbf{P}\mathbf{x}$ $\mathbf{P}$ is orthogonal matrix $\Rightarrow \|\mathbf{x}\| = \|\mathbf{y}\|$ 又作旋转变换/反射

$$\|\mathbf{y}\| = \sqrt{\mathbf{y}^T \mathbf{y}} = \sqrt{\mathbf{x}^T \mathbf{P}^T \mathbf{P} \mathbf{x}} = \sqrt{\mathbf{x}^T \mathbf{P}^T \mathbf{P} \mathbf{x}} = \sqrt{\mathbf{x}^T \mathbf{x}} = \|\mathbf{x}\|$$

<2> the eigenvalue of $\mathbf{P}$ is 1 or -1

$$\mathbf{A}\mathbf{v} = \lambda \mathbf{v} \quad (\mathbf{v} \neq \mathbf{0}) \quad \mathbf{v}^T \mathbf{A}^T = \lambda \mathbf{v}^T$$

$$\Rightarrow \mathbf{v}^T \mathbf{A}^T \mathbf{A} \mathbf{v} = \lambda \mathbf{v}^T \cdot \mathbf{A} \mathbf{v}$$

$$\mathbf{v}^T \mathbf{v} = \lambda \mathbf{v}^T \lambda \mathbf{v} = \lambda^2 \mathbf{v}^T \mathbf{v} \quad (\mathbf{v}^T \mathbf{v} \neq 0)$$

$$\Rightarrow \lambda = \pm 1$$

• Linear transform

1. $f(\alpha x + \beta y) = \alpha f(x) + \beta f(y)$

2. find the matrix representation of the linear transformation

[e.g. 1] $P_3 \rightarrow P_2$ $T: u \rightarrow \frac{du}{dx}$

P_3 basis $\{1, x, x^2, x^3\}$

P_2 basis $\{1, x, x^2\}$

$T(1) = \frac{d}{dx}(1) = 0 \cdot 1 + 0 \cdot x + 0 \cdot x^2$

$T(x) = \frac{d}{dx}(x) = 1 \cdot 1 + 0 \cdot x + 0 \cdot x^2$

$T(x^2) = \frac{d}{dx}(x^2) = 0 \cdot 1 + 2 \cdot x + 0 \cdot x^2$

$T(x^3) = \frac{d}{dx}(x^3) = 0 \cdot 1 + 0 \cdot x + 3 \cdot x^2$

$\Rightarrow A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \end{bmatrix}$

[e.g. 2] $T: P_2 \rightarrow P_3$ $T(f): x \rightarrow \int_0^x f(t) dt$

P_2 basis $\{1, x, x^2\}$

P_3 basis $\{1, x, x^2, x^3\}$

$T(1) = \int_0^x 1 dt = 0 \cdot 1 + 1 \cdot x + 0 \cdot x^2 + 0 \cdot x^3$

$T(x) = \int_0^x t dt = 0 \cdot 1 + 0 \cdot x + \frac{1}{2} \cdot x^2 + 0 \cdot x^3$

$T(x^2) = \int_0^x t^2 dt = 0 \cdot 1 + 0 \cdot x + 0 \cdot x^2 + \frac{1}{3} \cdot x^3$

$\Rightarrow A = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & \frac{1}{3} \end{bmatrix}$

3. basis transformation

basis α, β $\alpha \rightarrow \beta$:

$\beta = \alpha \cdot A$ $\swarrow$ 变换矩阵

向量 n 在 α, β 下坐标为 a, b

$(\alpha_1, \dots, \alpha_n) \cdot \begin{pmatrix} a_1 \\ \vdots \\ a_n \end{pmatrix} = (\beta_1, \dots, \beta_n) \cdot \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix}$

则 $\begin{bmatrix} a_1 \\ \vdots \\ a_n \end{bmatrix} = A \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix}$

$= (\alpha_1, \dots, \alpha_n) \cdot A \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix}$

$\Rightarrow \begin{pmatrix} a_1 \\ \vdots \\ a_n \end{pmatrix} = A \begin{pmatrix} b_1 \\ \vdots \\ b_n \end{pmatrix}$

• characteristic equation

$$A\lambda = \lambda x \Rightarrow (A - \lambda I)x = 0 \Rightarrow |A - \lambda I| = 0$$

* if $\lambda_1, \lambda_2, \dots, \lambda_m$ 是 n 个互异的 A 的 eigenvalues, 则 eigenvectors $\{v_1, \dots, v_m\}$ is linear independent.

Proof: ① $m=1, v_1 \neq 0 \Rightarrow \{v_1\}$ is linear independent

② Assume $m=k-1, \{v_1, v_2, \dots, v_{k-1}\}^*$ is linear independent. then Assume after adding $v_k, \{v_1, \dots, v_k\}$ is linear dependent.

$$\text{then } c_1 v_1 + \dots + c_{k-1} v_{k-1} = v_k \Rightarrow c_1 A v_1 + \dots + c_{k-1} A v_{k-1} = A v_k$$

$$\text{since } A v = \lambda v, c_1 \lambda_1 v_1 + \dots + c_{k-1} \lambda_{k-1} v_{k-1} = c_k \lambda_k v_k \quad \textcircled{2}$$

$$\textcircled{1} \times \lambda_k - \textcircled{2}: (c_1(\lambda_k - \lambda_1) v_1 + \dots + c_{k-1}(\lambda_k - \lambda_{k-1}) v_{k-1}) = 0$$

by *. we can conclude $c_1(\lambda_k - \lambda_1) = \dots = c_{k-1}(\lambda_k - \lambda_{k-1}) = 0$

$$\lambda_1, \dots, \lambda_k \text{ is pairwise distinct} \Rightarrow c_1 = c_2 = \dots = c_{k-1} = 0$$

by ①, $v_k = 0$, which contradict with $v_k \neq 0$ #

matrix	A	$aA+bE$	A^n	A^{-1}	A^*	A^T
eigenvalue	λ	$a\lambda+b$	λ^n	$\frac{1}{\lambda}$	$\frac{ A }{\lambda}$	λ
eigenvector	ζ	ζ	ζ	ζ	ζ	/

$$A\zeta = \lambda\zeta$$

$$(aA+bE)\zeta = aA\zeta + bE\zeta = a\lambda\zeta + b\zeta = (a\lambda+b)\zeta$$

$$A^n \zeta = A^{n-1} A \zeta = \lambda A^{n-1} \zeta = \lambda^n \zeta$$

$$A\zeta = \lambda\zeta \Rightarrow \frac{1}{\lambda}\zeta = A^{-1}\zeta$$

$$\frac{1}{\lambda}\zeta = A^{-1}\zeta \Rightarrow |A| \cdot A^{-1}\zeta = \frac{|A|}{\lambda}\zeta \Rightarrow A^*\zeta = \frac{|A|}{\lambda}\zeta$$

$$|A^T - \lambda E| = |A^T - \lambda E^T| = |(A - \lambda E)^T| = |A - \lambda E|$$

[e.g.] $AV_1 = \lambda_1 V_1, AV_2 = \lambda_2 V_2, (\lambda_1 \neq \lambda_2)$. Show $k_1 V_1 + k_2 V_2$ is not eigenvector of A

Proof: let $k_1 = k_2 = 1$, and assume $A(V_1 + V_2) = \lambda(V_1 + V_2)$

$$\Rightarrow AV_1 + AV_2 = \lambda_1 V_1 + \lambda_2 V_2 = \lambda(V_1 + V_2)$$

$$(\lambda_1 - \lambda)V_1 + (\lambda_2 - \lambda)V_2 = 0 \Rightarrow V_1, V_2 \text{ is linear independent}$$

$$\Rightarrow \lambda = \lambda_1 = \lambda_2 \text{ which contradicts with } \lambda_1 \neq \lambda_2$$

2. diagonalize

$P = (p_1, \dots, p_n)$ (P is a linear independent eigenvectors)

$$AP = (Ap_1, \dots, Ap_n) = (\lambda_1 p_1, \lambda_2 p_2, \dots, \lambda_n p_n) \\ = (p_1, \dots, p_n) \begin{pmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{pmatrix} = P \cdot \Lambda$$

$$\Rightarrow A = P \Lambda P^{-1} \quad \text{涉及求逆, 为简便计算} \rightarrow \text{正交对角化 } (A^T A = E \quad A^{-1} = A^T)$$

3. real symmetric matrices [实对称矩阵]

$$A \in \mathbb{R}^{n \times n} \text{ and } A = A^T$$

① all eigenvalues of A are real

$\Rightarrow$ try to prove $\bar{\lambda} = \lambda$

[$V^* = \bar{V}^T$ 共轭转置]

$$V^* A V = \lambda V^* V = \lambda \|V\|^2 \quad \Rightarrow \quad V^* A V = \lambda \|V\|^2 = (V^* A V)^* = (\lambda \|V\|^2)^* \\ (V^* A V)^* = V^* \underset{\substack{\downarrow \\ A^* = A^T = A}}{A} V = V^* A V = \bar{\lambda} \|V\|^2 \\ \Rightarrow \lambda = \bar{\lambda}$$

② $\star$ eigenvectors corresponding to different eigenvalues are orthogonal.

$$\begin{cases} Av_1 = \lambda_1 v_1 \\ Av_2 = \lambda_2 v_2 \end{cases} \Rightarrow \begin{cases} v_2^* A^* = \lambda_2 v_2^* \\ v_2^* A v_1 = \lambda_2 v_2^* v_1 \\ v_2^* A v_1 = \lambda_1 v_2^* v_1 \\ v_2^* \lambda_1 v_1 = \lambda_2 v_2^* v_1 \end{cases} \Rightarrow \lambda_1 v_2^* v_1 = \lambda_2 v_2^* v_1 \\ \text{Since } \lambda_1 \neq \lambda_2 \Rightarrow v_2^* v_1 = 0 \\ \text{i.e. } v_1, v_2 \text{ are orthogonal}$$

[e.g.] $A = \begin{pmatrix} 0 & -1 & 1 \\ -1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix}$ diagonalize

$$\begin{vmatrix} -\lambda & -1 & 1 \\ -1 & -\lambda & 1 \\ 1 & 1 & -\lambda \end{vmatrix} = 0 \Rightarrow \lambda_1 = -2, \lambda_2 = \lambda_3 = 1$$

$$\Rightarrow p_1 = \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix}, p_2 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, p_3 = \begin{pmatrix} 0 \\ 1 \\ 1 \end{pmatrix} \Rightarrow P = \begin{pmatrix} -\frac{1}{\sqrt{3}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \\ -\frac{1}{\sqrt{3}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{6}} \\ \frac{1}{\sqrt{3}} & 0 & \frac{2}{\sqrt{6}} \end{pmatrix}$$

$$v_1 = \frac{1}{\sqrt{3}} \begin{pmatrix} -1 \\ -1 \\ 1 \end{pmatrix}, v_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, v_3 = \frac{1}{\sqrt{6}} \begin{pmatrix} 1 \\ 1 \\ 2 \end{pmatrix}$$

③ spectral theorem 谱定理 [不是所有矩阵能被对角化 几何重数 = 代数重数]

Any real symmetric matrix A can be written as $A = V D V^T$

(V is a real orthogonal matrix / D is a real diagonal matrix)

4. similar matrices

$A, B \in \mathbb{R}^{n \times n}$ satisfy $A = S B S^{-1}$ for some $S \in \mathbb{R}^{n \times n}$ invertible

$\Rightarrow A$ and B are similar ($A \sim B$)

$$\textcircled{1} \text{IG}(A) = \bar{E} \text{IG}(B)$$

$$P_A(\lambda) = \det(A - \lambda I) = \det(SBS^{-1} - \lambda SS^{-1}) = \det(S(B - \lambda I)S^{-1})$$

$$= \det(B - \lambda I) \cdot |S| \cdot \frac{1}{|S|} = \det(B - \lambda I) = P_B(\lambda)$$

$$\textcircled{2} \text{tr}(A) = \text{tr}(B) \quad \det(A) = \det(B)$$

$$\text{tr}(A) = \text{tr}((S^{-1}B)S) = \text{tr}(S(S^{-1}B)) = \text{tr}(B) \quad \star \text{tr}(MN) = \text{tr}(NM)$$

$$\det(A) = \det(S^{-1}BS) = \det(S^{-1}) \cdot \det(S) \cdot \det(B) = \det(B)$$

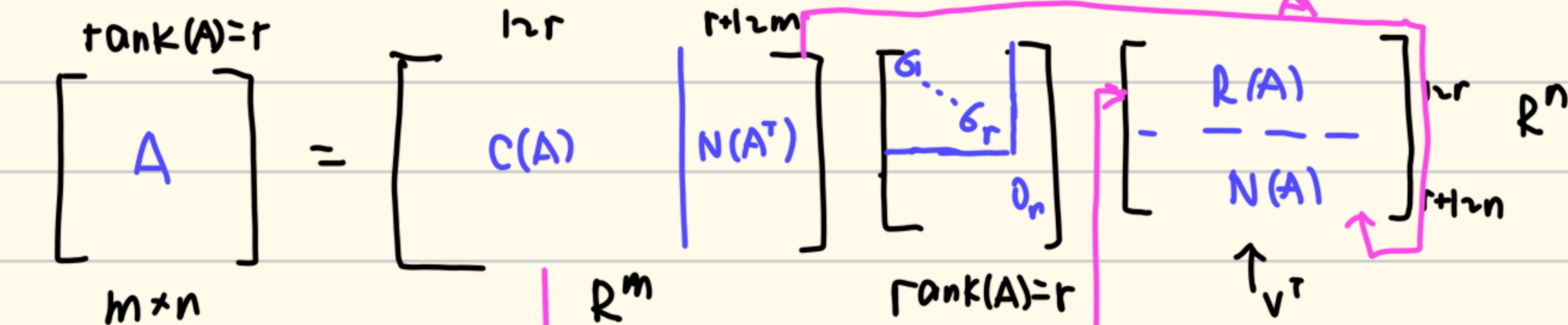
5. SVD decomposition

A 非对称 $\Rightarrow AA^T / A^T A$ 实对称

$$\begin{cases} AA^T = P S^2 P^T \\ A^T A = Q S^2 Q^T \end{cases} \Leftrightarrow A = P S Q^T \Rightarrow A Q = P S \Rightarrow P_i = \frac{A q_i}{s_i}$$

$\downarrow \sigma_i = \sqrt{\lambda_i} > 0$

• the relationship between SVD decomposition and four fundamental subspaces



$$A = U \Sigma V^T$$

$$U_1 = [u_1, \dots, u_r], U_2 = [u_{r+1}, \dots, u_m]$$

$$V_1 = [v_1, \dots, v_r], V_2 = [v_{r+1}, \dots, v_n]$$

$v_i \xrightarrow{A} u_i$

$A \vec{v}_i = \vec{u}_i \cdot \vec{\sigma}_i$

$$\textcircled{1} A \in \mathbb{R}^{m \times n}, \quad R(A) = \{Ax \mid x \in \mathbb{R}^n\} \subseteq \mathbb{R}^m$$

$$A = \sum_{i=1}^r \sigma_i u_i v_i^T = \sum_{i=1}^r \sigma_i u_i v_i^T$$

$$y = Ax = \sum_{i=1}^r (\sigma_i v_i^T x) u_i = \sum_{i=1}^r \alpha_i u_i = C(A) = C(U_1)$$

$$\textcircled{2} Ax = \sum_{i=1}^r \sigma_i u_i v_i^T x \quad \text{let } z = \sum_{i=r+1}^n \beta_i v_i$$

$$Az = \left(\sum_{i=1}^r \sigma_i u_i v_i^T \right) \left(\sum_{i=r+1}^n \beta_i v_i \right) = 0 \Rightarrow N(A) = \{x \mid Ax = 0\} = C(V_2)$$

$$\textcircled{3} R(A^T) = R(A) = C(V_1)$$

$$\textcircled{4} N(A^T) = C(U_2)$$

• application

1. pagerank [eigenvalue]

- ① construct a matrix A (其他点链接到该点的概率)
- ② $V^{(t+1)} = AV^{(t)}$ iteration
- ③ $V = AV$ 趋于稳定
 $\Rightarrow V$ is an eigenvector of A whose eigenvalue is 1

2. Dynamics [diagonalization]

$$\begin{pmatrix} u_{k+1} \\ v_{k+1} \end{pmatrix} = \begin{pmatrix} \alpha_1 & \alpha_2 \\ \beta_1 & \beta_2 \end{pmatrix} \begin{pmatrix} u_k \\ v_k \end{pmatrix} \Rightarrow \vec{z}_k = A^k \cdot \vec{z}_0$$

$\vec{z}_{k+1} \qquad \qquad \vec{z}_k$

[eg.] predator-prey Model

Q12 Given a year $k \in \mathbb{N}$, let us denote $x_k, y_k \in \mathbb{N}$, respectively, the number of rabbits and the number of wolves and let us assume they satisfy the equations:

$$\begin{cases} x_{k+1} = 1.2x_k - 0.2y_k \\ y_{k+1} = 0.3x_k + 0.5y_k \end{cases}$$

Introducing $A = \begin{pmatrix} 1.2 & -0.2 \\ 0.3 & 0.5 \end{pmatrix}$, $u = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$, $v = \begin{pmatrix} 1 \\ 3 \end{pmatrix}$, $\lambda_1 = 1.1$, $\lambda_2 = 0.6$, one can show that $Au = \lambda_1 u$ and $Av = \lambda_2 v$. Assuming that at year 0, $x_0 = 100$, $y_0 = 40$, deduce a simple expression of x_k, y_k for any $k \in \mathbb{N}$ as a function of k, λ_1, λ_2 .

$$\begin{pmatrix} x_{k+1} \\ y_{k+1} \end{pmatrix} = \begin{pmatrix} 1.2 & -0.2 \\ 0.3 & 0.5 \end{pmatrix} \begin{pmatrix} x_k \\ y_k \end{pmatrix} \qquad A = S \Lambda S^{-1} = \begin{pmatrix} 2 & 1 \\ 1 & 3 \end{pmatrix} \begin{pmatrix} 1.1 & 0 \\ 0 & 0.6 \end{pmatrix}^{\frac{1}{5}} \begin{pmatrix} 3 & -1 \\ -1 & 2 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} x_k \\ y_k \end{pmatrix} = \begin{pmatrix} 2 & 1 \\ 1 & 3 \end{pmatrix} \begin{pmatrix} 1.1^k & 0 \\ 0 & 0.6^k \end{pmatrix}^{\frac{1}{5}} \begin{pmatrix} 3 & -1 \\ -1 & 2 \end{pmatrix} \cdot \begin{pmatrix} 100 \\ 40 \end{pmatrix}$$

3. compression [SVD]

low-rank approximation

$$A_k = \sum_{i=1}^k \sigma_i u_i v_i^T \qquad \min_X \|A - X\|_F \qquad \text{rank}(X) = k \qquad X = A_k$$

$$(\sigma_1 \geq \sigma_2 \geq \dots \geq \sigma_k \geq \sigma_{k+1} \geq \dots \geq \sigma_r > 0)$$

$$\textcircled{1} \|B\|_F^2 = \text{tr}(B^T B)$$

$$C = B^T B \qquad C_{i,j} = \sum_{k=1}^m B_{ki}^T \cdot B_{kj} = \sum_{k=1}^m B_{ki} \cdot B_{kj}$$

$$\text{tr}(B^T B) = \sum_{i=1}^n \sum_{k=1}^m B_{ki}^2 = \|B\|_F^2$$

$$\textcircled{2} \|A\|_F = \sqrt{\text{tr}(AA^T)} = \sqrt{\sigma_1^2 + \dots + \sigma_r^2}$$

$$\Rightarrow \|A - A_k\|_F = \sqrt{\sigma_{k+1}^2 + \dots + \sigma_r^2}$$

4. curve classification [quadratic forms]

$$x^T A x = C$$

$$\textcircled{1} A = U D U^T$$

$$\textcircled{2} z = U^T x$$

$$\textcircled{3} x^T A x = z^T D z = C \Rightarrow \sum d_i z_i^2 = C$$

$$\textcircled{4} \text{ eigenvalues of } A \begin{cases} ++ / -- & \text{ellipsoid} \\ +- & \text{hyperbola} \\ \lambda_i = 0 & \text{parabola} \end{cases}$$

e.g.] $5x_1^2 - 6x_1x_2 + 5x_2^2 = 4$

$$A = \begin{bmatrix} 5 & -3 \\ -3 & 5 \end{bmatrix}$$

$$\lambda_1 = 8, \lambda_2 = 2$$

$$z = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}^T \cdot x$$

$$\Rightarrow \frac{z_1^2}{0.5} + \frac{z_2^2}{2} = 1 \text{ ellipsoid}$$